

176  
177 arcCyl = trimatic.create\_circle\_arc\_3\_points(arc\_points[0], arc\_points[1], arc\_points[2])  
178 arcCyl.name = 'arcCylinder'  
179 trm.delete(arc\_points)  
180 arcOriginM = trm.create\_point(arc\_points[0])  
181 arcNormM = trm.create\_point(arc\_points[1])  
182 dpCylinder = trm.create\_dome(arcCyl, arcOriginM, arcNormM)  
183  
184 if debug == 0:  
185 trm.delete(arcCyl)  
186 trm.delete(arcOriginM)  
187 trm.delete(arcNormM)  
188  
189 # open mastoid shell  
190 stlReader = vtk.vtkSTLReader()  
191 stlReader.SetFileName(mastoid.stl)  
192 stlReader.MergeOn()  
193 stlReader.Update()  
194  
195 points = vtk.vtkPoints()  
196 triangles = vtk.vtkCellArray()  
197  
198 mesh = stlReader.GetOutput()  
199 points = mesh.GetPoints()  
200 dataArray = points.GetData()  
201 numberOfFaces = mesh.GetNumberOfFaces()  
202 numberOfPoints = mesh.GetNumberOfPoints()  
203 # now we have a vtkData object now  
204 # we can use it to store thickness and surface flatness

Michael Sharkey  
Clinical Scientist  
and Medical Physics.

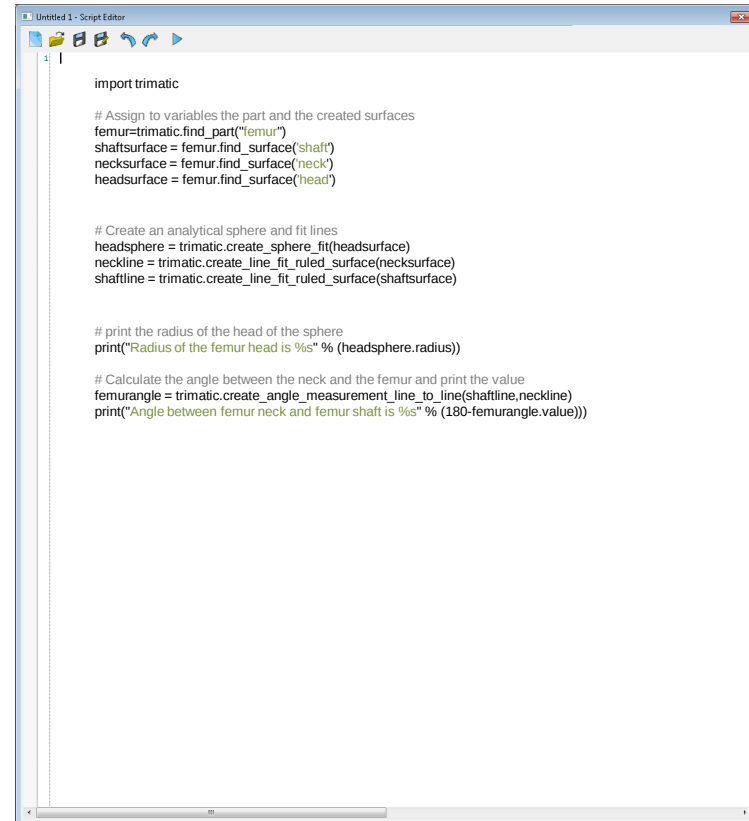
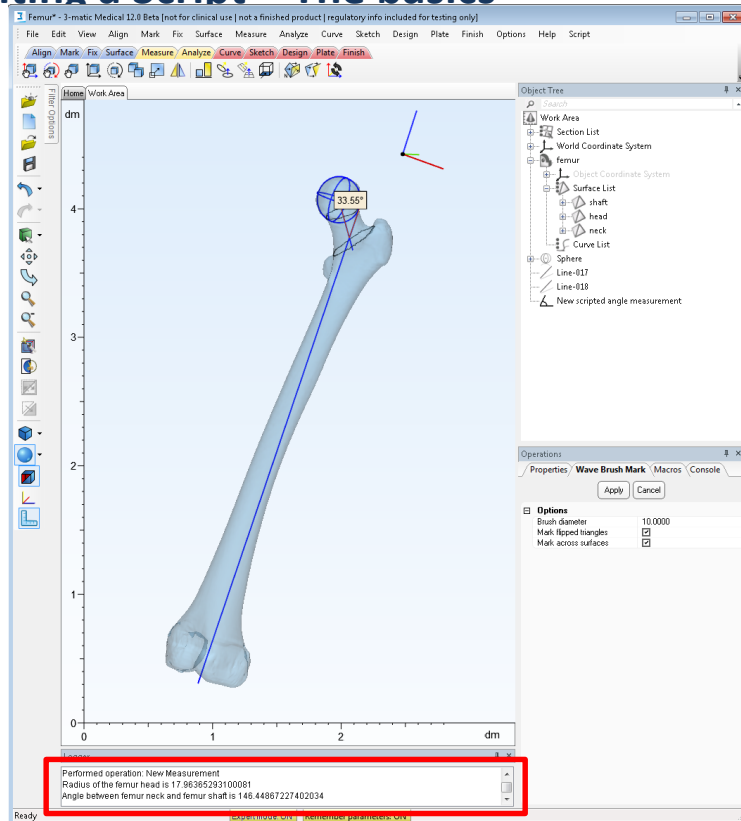
Sheff

&

## Clinical Scientist

3DLAB  
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# Writing a Script – The basics



## Case Study 1 - Automatically fitting a bone conduction implant

### ENT Surgical Planning Bone Conduction Implant

- Bone conduction implant that transmits sound waves via the cranial bone directly to the inner ear.
- The floating mass transducer is buried into the temporal bone.
- Requirement to ensure there is sufficient bone to accommodate the device.

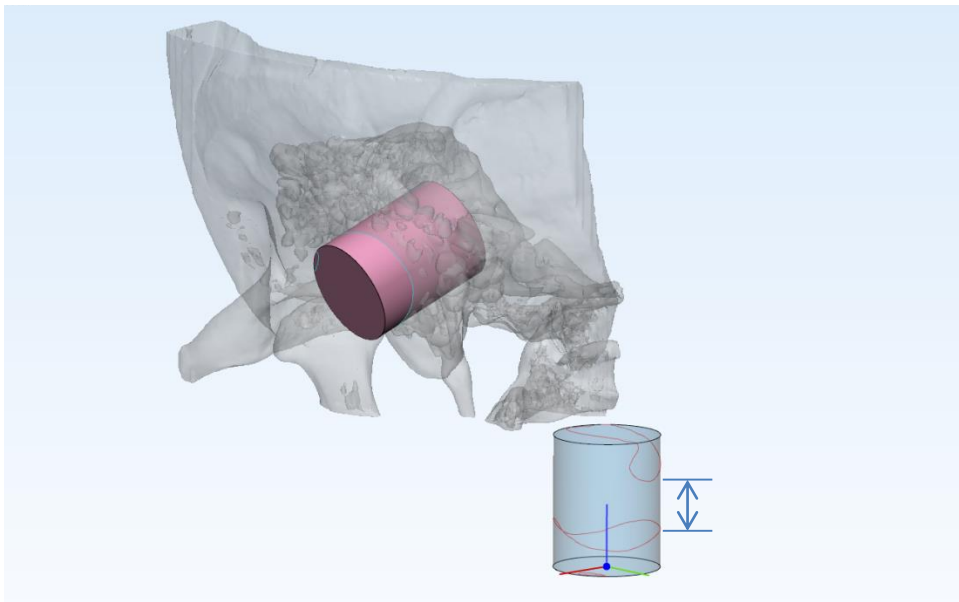


<http://www.medel.com/uk/bonebridge/>

## Case Study 1 - Automatically fitting a bone conduction implant

Determine the direction of the implant:

→ Move cylinder back to the origin & analyse intersection curves



### Curve Analysis

- Determine which curve is at the external bone surface (could be multiple curves)
- Measure distance from mean external height to minimum height of internal surface curve

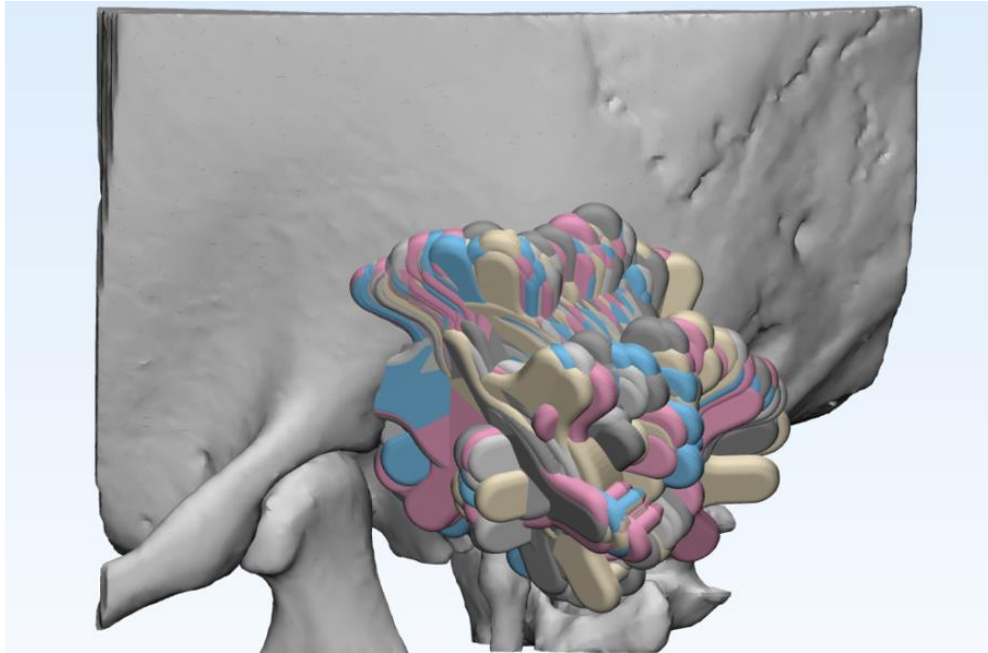
→ Bone thickness

**Does the device fit**



## Case Study 1 - Automatically fitting a bone conduction implant

### Full Analysis:



### Device fitting

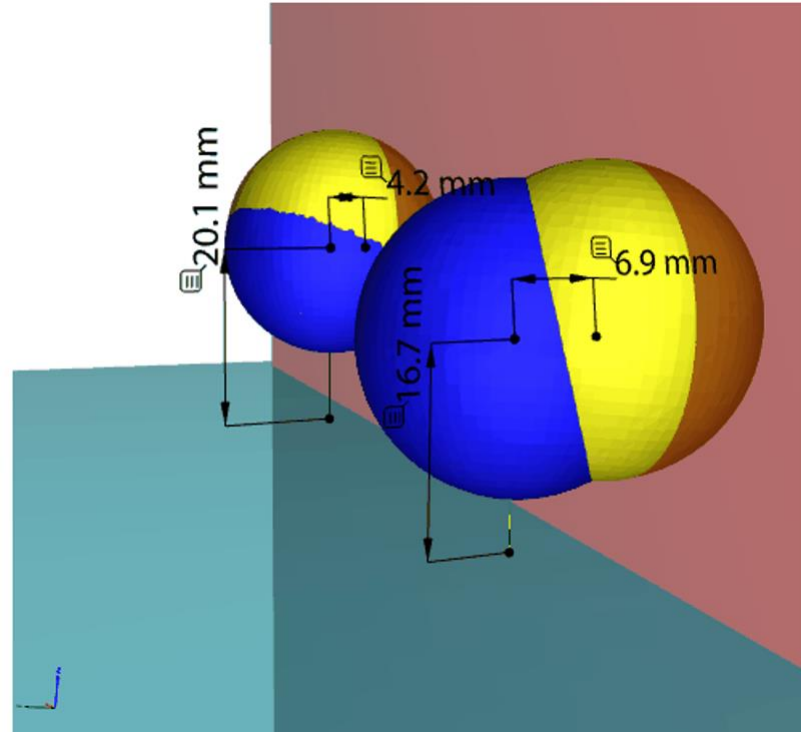
- Analysis performed at every position
- 1000 nodes ~ 2.5h hours
- Which is the best position?
- Score thickness & surface variation

## Case Study 2 - Pre and post surgical measurements for enophthalmos evaluation

Maxio-facial reconstruction following trauma to the eye socket

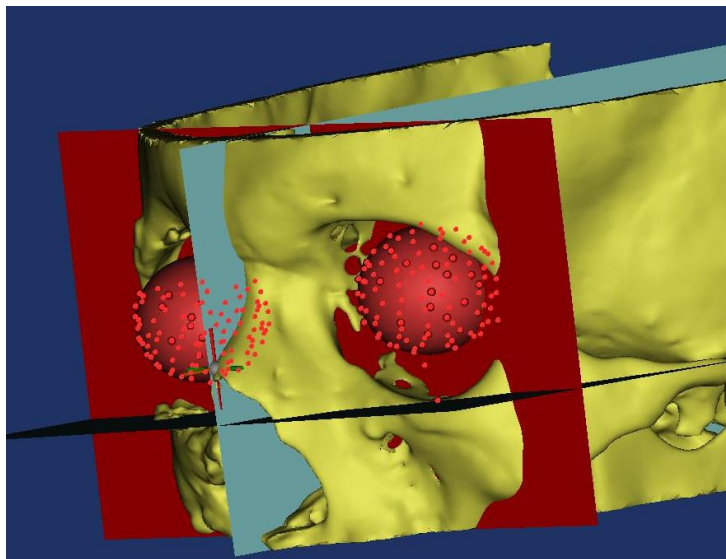
Surgical Implant inserted to re-align the displaced orbit

- Pre-surgical cone-beam CT (CBCT) scan to determine the extent of the displacement
- Post-surgical CT scan to determine the final position of the orbit
- Can we perform a CT enophthalmos evaluation and determine the pre to post displacement?



## Case Study 2 - Pre and post surgical measurements for enophthalmos evaluation

### Mimics – Manually define anatomical planes & export as 3D structures



```
147
148 def definePlanes():
149     ...
150     Defines points on the Frankfurter plane, the sagittal midline plane and a coronal frontal plane b
151     ...
152
153 pt_list = np.zeros((4, 3), dtype=np.float32)
154 print('Select points in the following order:')
155 print('  1) The left external auditory canal')
156 print('  2) The right external auditory canal')
157 print('  3) The inferior orbital rim on the undamaged side')
158 print('  4) The lateral orbital rim on the undamaged side')
159
160 lt_pt = mimics.analyze.indicate_point(title='Left external auditory canal', message='Please indicate point')
161 pt_list[0] = lt_pt.coordinates
162 rt_pt = mimics.analyze.indicate_point(title='Right external auditory canal', message='Please indicate point')
163 pt_list[1] = rt_pt.coordinates
164 orbital_pt = mimics.analyze.indicate_point(title='Undamaged inferior orbital rim', message='Please indicate point')
165 pt_list[2] = orbital_pt.coordinates
166 lat_pt = mimics.analyze.indicate_point(title='Undamaged lateral orbital rim', message='Please indicate point')
167 pt_list[3] = lat_pt.coordinates
168
169 return pt_list
170
```

## Conclusions

- Scripting in Mimics and 3-matic offers great opportunities to automate processing
- Speeds up repetitive tasks
- Improves reproducibility
- Enables tasks which would be otherwise impossible

